

## # Implementation at the DVIC (as of August 2020)

Getting up to speed with the Crazyflie isn't too difficult, as its functionalities are neatly packaged. A first flight of the platform makes use of a keyboard control algorithm, which we detail in our Crazyflie flight project. We use this to check that the drone is in a working state. Its python API is useful for prototyping applications.

A video gives a quick overview of why as a lab we chose this drone over any other.

